# TERRAS ND°

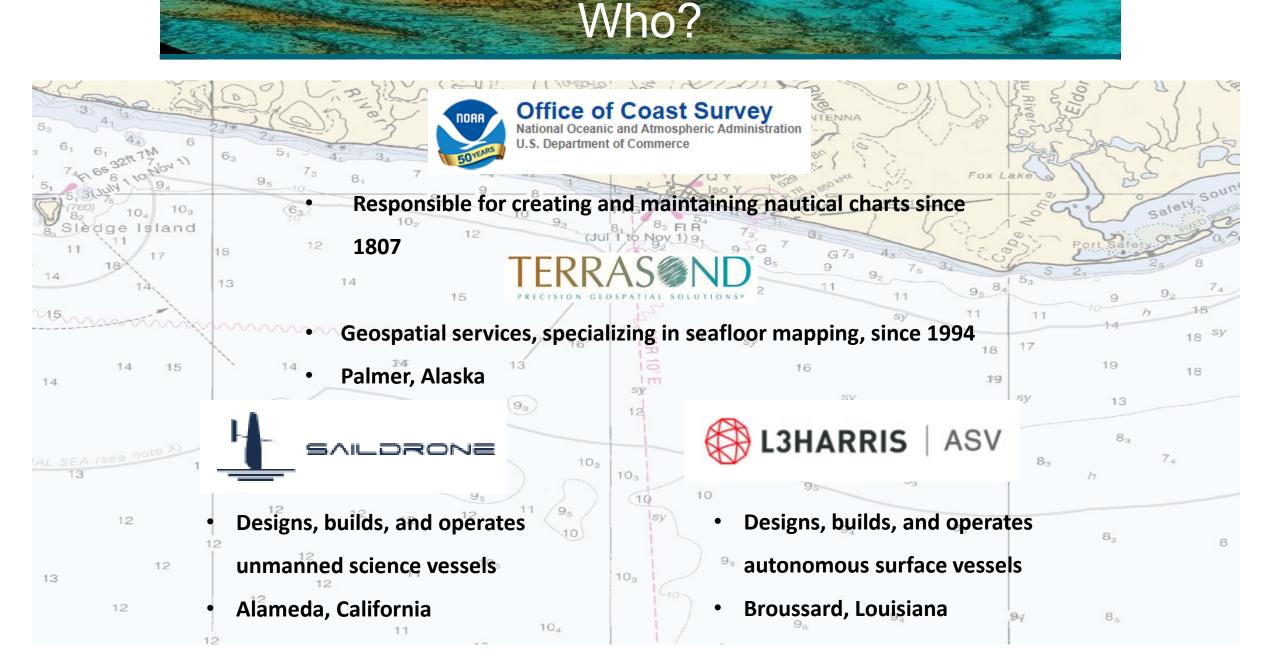
terra \terə\ n. [Latin] *the planet earth; land or territory* 

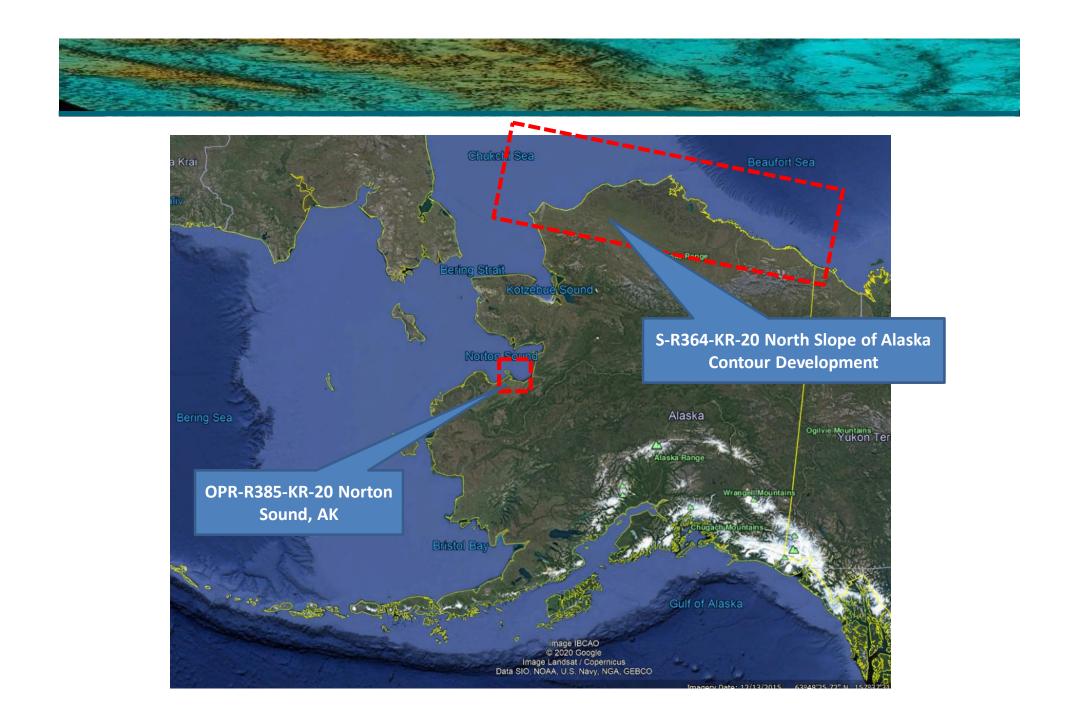
sond \sänd\ n.f. [French] an instrument for measurement

### 2020 Unmanned Vessel Deployments: ASV and Saildrone

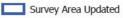
Andrew Orthmann, TerraSond Charting Program Manager

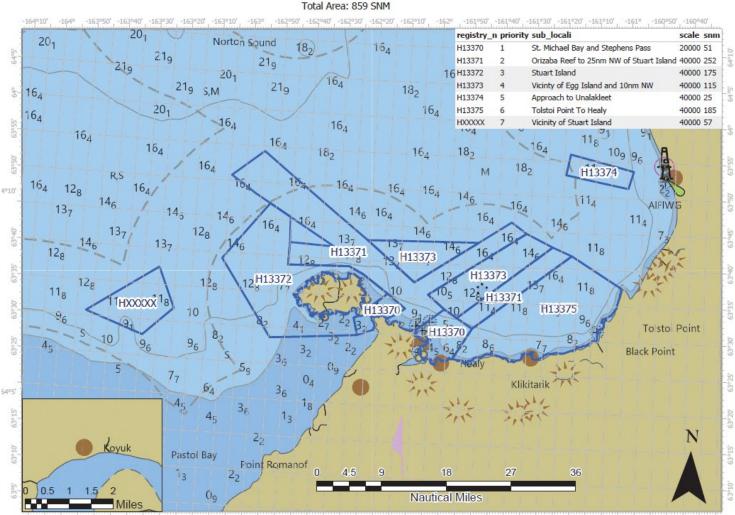
www.terrasond.com





#### OPR-R385-KR-20 - Norton Sound, AK





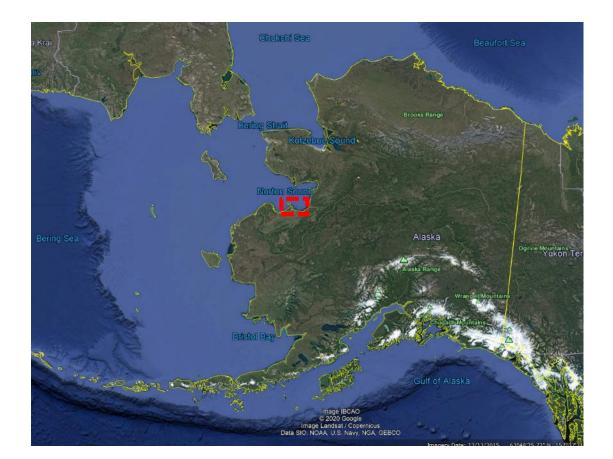
And Andrew Parks and Andr

- Standard NOAA charting survey
- 859<sup>2</sup> nautical miles
- 20m to 2m water depth
- Multibeam sonar coverage

4° - 163°50' - 163°40' - 163°30' - 163°20' - 163°10' - 163°50' - 162°50' - 162°40' - 162°30' - 162°20' - 162°10' - 161°50' - 161°50' - 161°30' - 161°20' - 161°10' - 161°10' - 160°40' - 161°40' - 161°40' - 161°40' - 161°40' - 161°40' - 160°40' - 16

- Remote area
- Long transit (>1,000 NM)
- Large amount of data collection (>9,000 LNM)
- Limited season to work due to weather and ice

- Requires good production rates
- Ability to work shallow water
- Traditionally done with ship and manned launches



- TerraSond began using unmanned vessels on Alaska projects in 2015 with a military drone modified for survey
- L3 Harris ASV 🛞 L3HARRIS | ASV
- Good experiment but issues with endurance, deployment, and payload capabilities

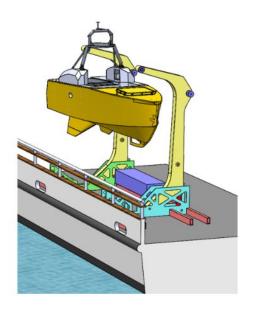


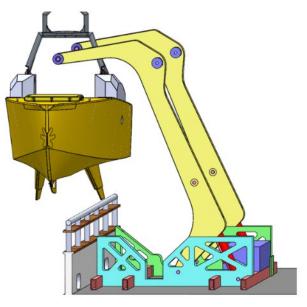




- L3 Harris ASV C-Worker 5 (CW5) starting in 2016
- 18' unmanned vessel, purpose-built for survey
- Launch and Recovery System (LARS)
- Greater survey equipment options
- Endurance up to 7 days continuous survey







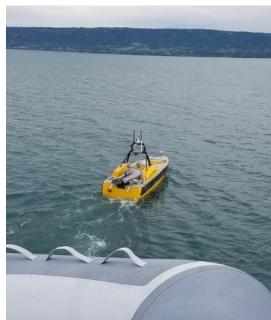


- Mobilize on a 105' "mother" vessel
- Mother vessel mods: LARS install, radio antennas, container on

deck to support additional personnel







- Works alongside the larger vessel 24/7 as a "force multiplier"
- Collecting the same data types as the larger vessel on parallel

#### survey lines



- Also relied on to work shallow water unsafe for larger vessel
- Shallow draft, maneuverable



- Radio links for control and data, 2-3 km reliable range
- Two technicians per shift: 1 ASV control, 1 survey
- Not fully "autonomous": Unmanned but continuously monitored
- Entirely remote controlled at times



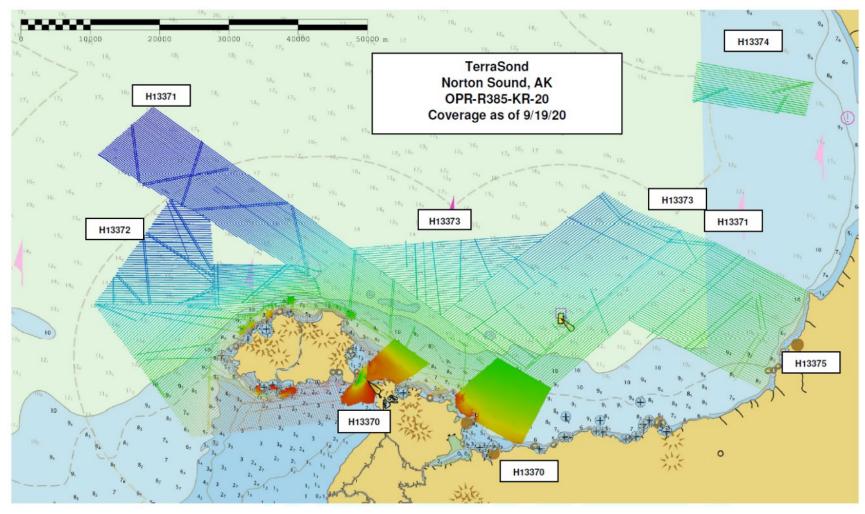
Survey Equipment Control / Monitoring

ASV Control / Monitoring

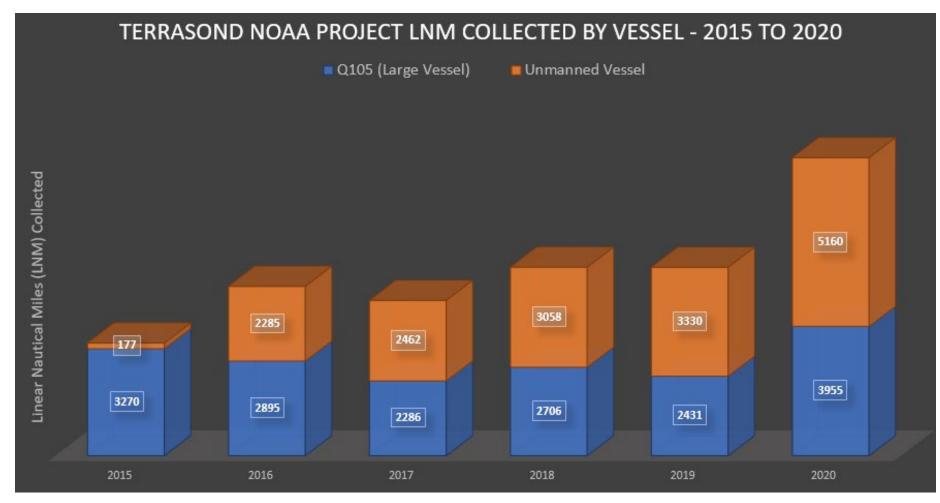
- Norton Sound Survey Area
- July September, 2020

• Required collection of 9,100

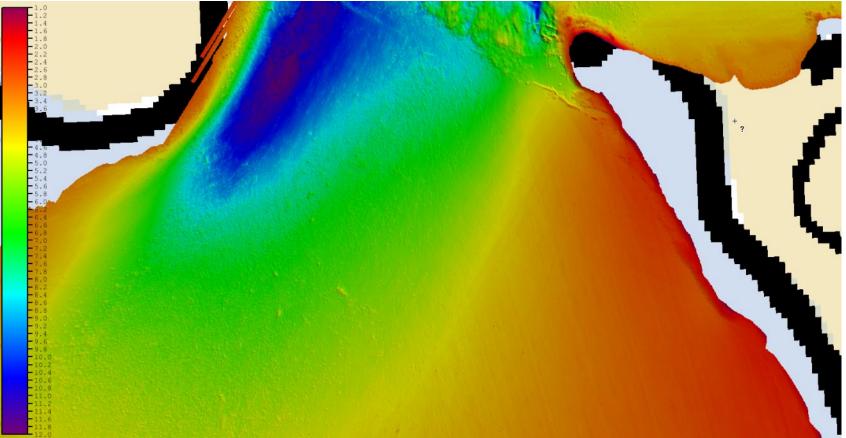
LNM of multibeam sonar data



- CW5 ASV acquired most of the data on the project (~ 57%, or 5160 of 9115 LNM)
- Continues a trend of increasing unmanned vessel LNM since 2015

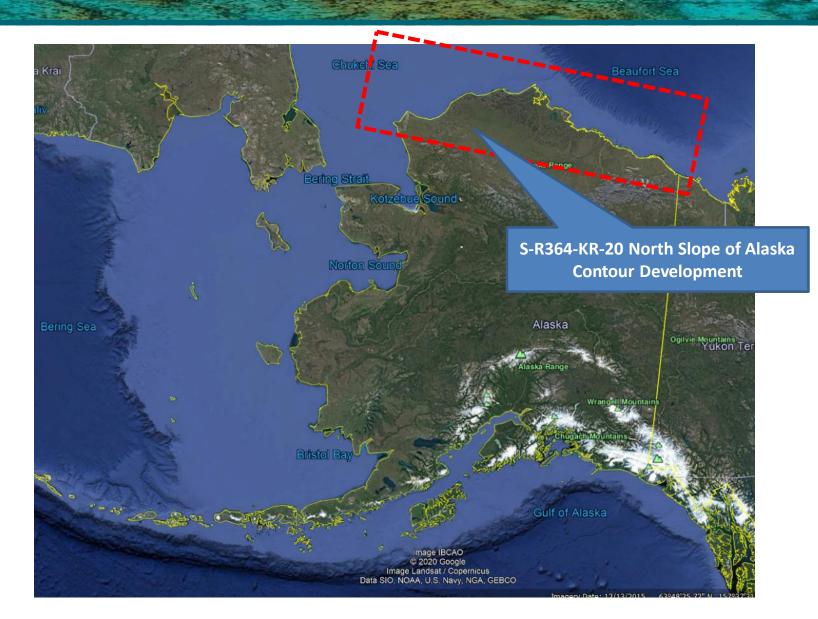


Example multibeam (Reson T50) data collected with the CW5 ASV in Stephens Passage:



Stuart
Stuart<

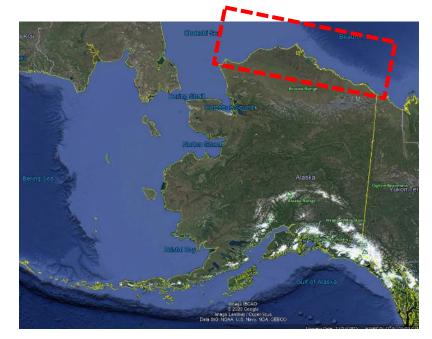
 Processing of dataset in progress; will be delivered to NOAA OCS in January for application to nautical charts



#### **Primary Mission Objectives:**

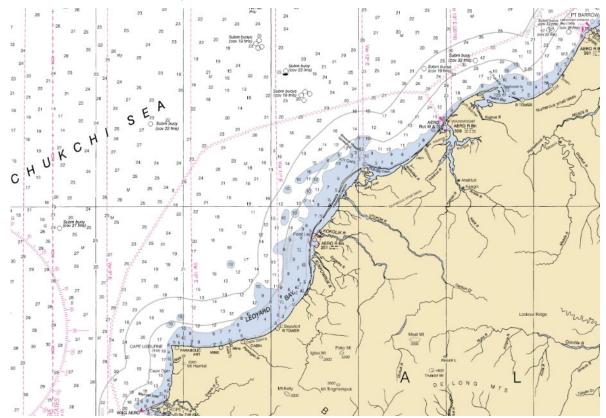
- Locate 20 m (65') and 50 m (164') depth curves off the North Slope to assist with planning future surveys
- Demonstrate ability to accomplish unmanned seafloor surveys in remote areas
- Test feasibility of saildrone technology for mapping and derive lessons learned





- Ocean off of Alaska's North Slope are poorly charted
- The Arctic area is of increasing priority for chart updates
- The area is difficult and expensive to reach with conventional means (large vessel with

launches)





NOAA ship Fairweather – example of conventional survey approach

- Unmanned science vessel (USV)
- Wind-driven sailboat (no engine or prop)
- Slow, normally 2-3 knots
- Solar panels for electronics, zero emissions
- 23' length, 16' height, 8' draft
- World-wide range, up to 1 year durations

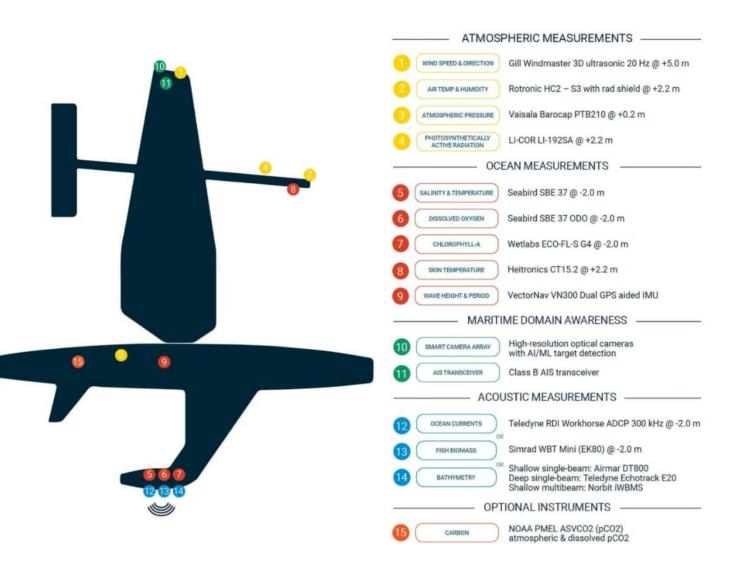




• Carries suite of scientific instruments

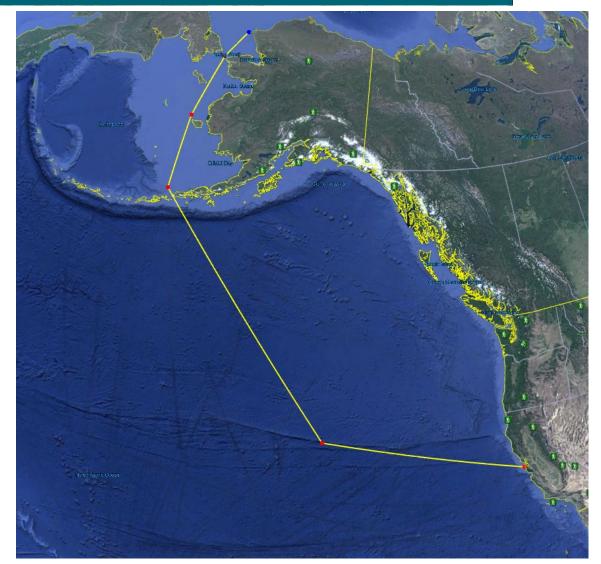
- Highly visible, includes AIS, lights, radar reflectors, and cameras
- Remotely monitored by satellite
- User access through online web portal

Standard Saildrone Sensor Suite

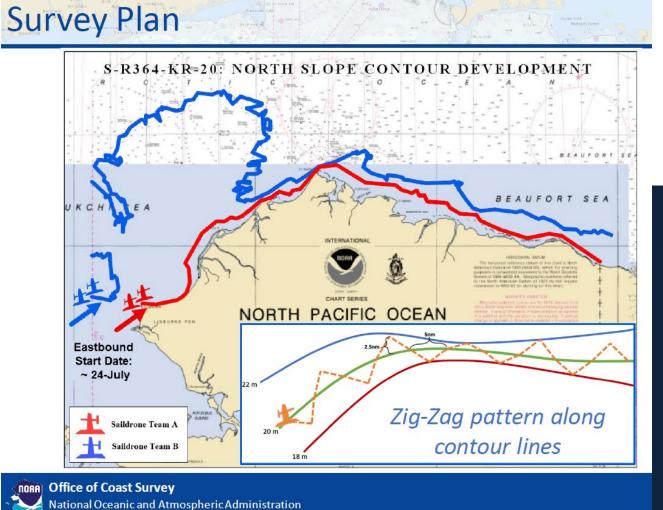


**California to Alaska:** 

- Four saildrones were used: SD1037, 1055, 1068, and 1069.
- Not feasible to launch from Alaska due to COVID19 travel restrictions
- Departed San Francisco, California May 28<sup>th</sup>, 2020
- Began to arrive off Point Hope August 2<sup>nd</sup>, 2020 (66 days)
- About 3000 nautical mile transit

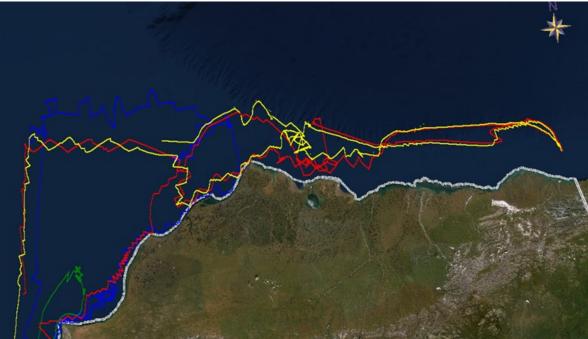


Approximate route the saildrones took from San Francisco to Pt. Hope



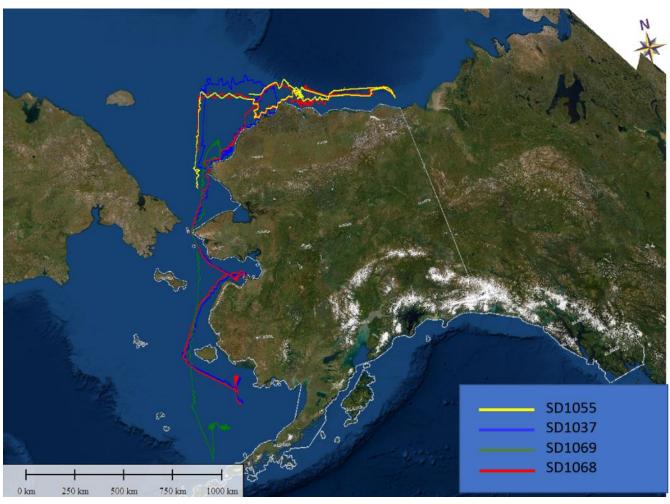
#### Planned vs Actual:

- Ice pack encountered
- Early bowhead whale migrations
- Equipment issues



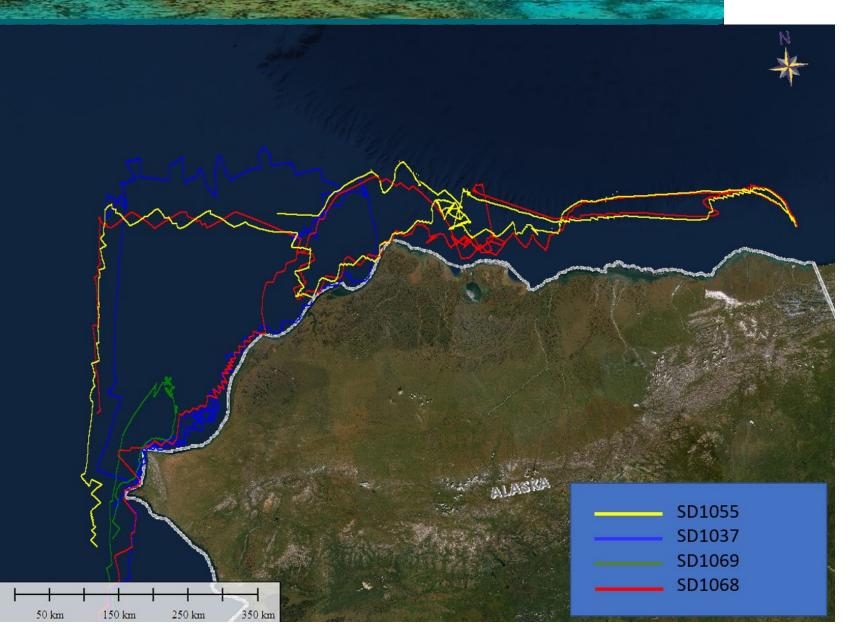
#### Following the Arctic mission:

- All south of Pt. Hope by 9/26
- Did additional work in Norton Sound and Kuskokwim Bay
- Departed Alaska 10/31, three arrived California by 12/2, one damaged in a storm and still in transit
- Dataset will be delivered to NOAA OCS in February for review and application to nautical charts



Overview of the saildrone's operations in Alaska this season.

- 4,300 nautical miles new sounding data Pt. Hope to the Canadian Border
- Proof of concept for using unmanned vessels for remote surveys, especially capability to work during COVID19
- Lessons learned sending unmanned vessels to/from the Arctic



#### Summary

- Two different use scenarios: Force multiplier and independent (unaccompanied) ops
- Both with clear benefits to safety, productivity, and capabilities
- We will continue to deploy and help develop the technology

Special Thanks to:

- NOAA OCS
- Saildrone, Inc. and L3 Harris ASV







Independent / unaccompanied operations

