REGIONAL TSUNAMI HAZARD ASSESSMENT FOR ANDREANOF ISLANDS, ALASKA

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REGIONAL TSUNAMI HAZARD ASSESSMENT FOR ANDREANOF ISLANDS, ALASKA

E.N. Suleimani,¹ D.J. Nicolsky,¹ R.D. Koehler,² and J.B. Salisbury²

Abstract

We assess potential tsunami hazard for the central Aleutian communities of Adak and Atka, on the Andreanof Islands, Alaska. The primary tsunami hazard for these communities is considered to be near-field, with the major threat originating from tsunamigenic earthquakes along the Alaska-Aleutian megathrust. We numerically model tsunamis generated by three different megathrust earthquakes, analyze tsunami wave dynamics, and develop tsunami hazard maps for the coastal communities of Adak and Atka. The hypothetical tsunami scenarios that we examined simulate $M_{\rm w}9.0$ megathrust earthquakes with a slip distribution in the 5-35 km (3-22 mi) depth range along the Alaska-Aleutian megathrust. The maximum runup heights are 23.4 m (76.8 ft) in Adak and 31.1 m (102 ft) in Atka. Results presented here are intended to provide guidance to local emergency management agencies in initial tsunami inundation assessment, evacuation planning, and public education for mitigation of future tsunami hazards.

INTRODUCTION

Subduction of the Pacific plate under the North American plate has resulted in numerous great earthquakes and has the highest potential to generate tsunamis in Alaska (Dunbar and Weaver, 2008). The Alaska-Aleutian megathrust (fig. 1), the fault formed by the Pacific-North American plate interface, produces the majority of large earthquakes in the U.S. (ComCat, the ANSS Comprehensive Earthquake Catalog, https://earthquake.usgs.gov/ data/comcat/). The latest sequence of great earthquakes along the Alaska-Aleutian megathrust began in 1938 with a M_w8.3 earthquake west of Kodiak Island (Estabrook and others, 1994). Four subsequent events, the 1946 M_w8.6 Aleutian (Lopez and Okal, 2006), the 1957 M_w8.6 Andreanof Islands (Johnson and Satake, 1993), the 1964 M_9.2 Alaska (Kanamori, 1970), and the 1965 M_w8.7 Rat Island (Wu and Kanamori, 1973) earthquakes, ruptured almost the entire length of the megathrust. Tsunamis generated by these great earthquakes reached Alaska coastal communities within minutes and resulted in widespread damage and loss of life (National Centers for Environmental Information/ World Data Service [NCEI/WDS]). Saving lives and property in the future depends on community preparedness, which further depends on estimating potential flooding of the coastal zone in the event of a local or distant tsunami.

The future occurrence of earthquakes and tsunamis necessitates the development of inundation and tsunami evacuation maps for use in tsunami hazard mitigation. In this report, we provide an analysis of numerical modeling of tsunamis and develop tsunami hazard maps³ for the communities of Adak and Atka, the two largest communities on the Andreanof Islands. This report is intended for use by scientists, engineers, and planners interested

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³This report is different than previous reports (such as Nicolsky and others, 2013, 2014; Suleimani and others, 2013, 2014, 2015), in which the authors completed a thorough sensitivity study and considered numerous tsunami sources. In this assessment we base an estimation of the potential inundation zone only on three significant tsunami scenarios. Although the modeled tsunami inundation cannot be considered exhaustive, it is still thought to provide a sound approximation of the potential tsunami inundation zone in the communities.

in applying modeling results to develop tsunami inundation and evacuation maps. Digital data and documentation provided with the report enable technical users to explore the range of potential tsunami hazards expected in future events.

PROJECT BACKGROUND: REGIONAL AND HISTORICAL CONTEXT

Community Profiles

The community of Adak (51.53'0"N, 176.38'42"W), population 247, is located on Adak Island, in the Andreanof Islands (fig. 1). It is 1,930 km (1,200 mi) southwest of Anchorage and 724 km (450 mi) west of Dutch Harbor. According to the Alaska Department of Commerce, Community, and Economic Development, Division of Community and Regional Affairs (DCCED/DCRA, 2013), Adak Island, once heav-

ily populated, was abandoned in the early 1800s as the Aleutian Islands hunters followed the Russian fur trade eastward. During World War II, Adak's military installations allowed U.S. forces to mount successful military operations. After the war, Adak was developed as a Naval Air Station, which closed on March 31, 1997. In 2001, a community formed as a second-class city. Adak currently provides a fueling port and crew transfer facility for fishing ships based in Seattle and Alaska. The community has an airport, docks, housing facilities, a restaurant, grocery store, and ship supply store. Adak Fisheries, LLC, an employer of a large seasonal staff, processes Pacific cod, pollock, mackerel, halibut, and snow and king crab.

The small community of Atka (52°11'57" N, 174°12'48" W), population 70, is on the east side of Atka Island in the Andreanof Islands (fig. 1). It is 1,770 km (1,100 mi) southwest of Anchor-

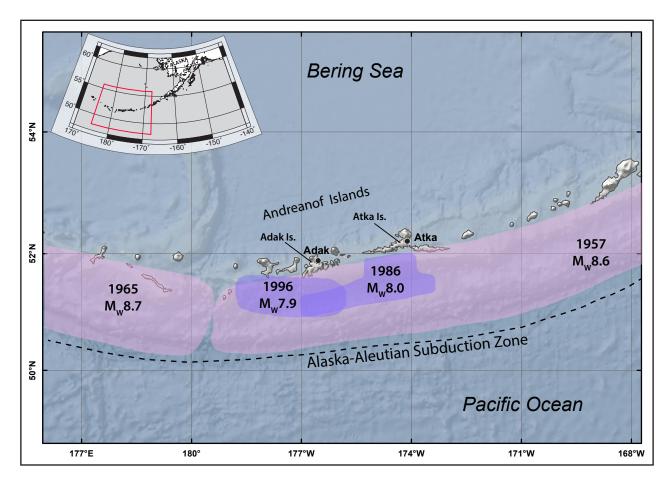


Figure 1. Map of the central Aleutian Islands and the Andreanof Islands group. Rupture areas of the latest sequence of great and large earthquakes are shown by shaded polygons.

age, 563 km (350 mi) west of Dutch Harbor, and 172 km (107 mi) east of Adak. Atka is a traditional Unangan (Aleut) community and a federally recognized tribe. According to DCCED/ DCRA (2013), the island has been occupied by Unangans for at least 2,000 years. The first contact with Russians occurred in 1747, and Atka became an important trade site and safe harbor. During World War II, Atka was burned to the ground but was rebuilt by the U.S. Navy after the war, at which time residents were allowed to return. The city was incorporated in 1988. The community has an airport, docks, and housing facilities. Scheduled air services are available three times weekly from Unalaska, and planes can also be chartered to the community from Cold Bay or Unalaska.

Seismic and Tsunami History

The rate of plate convergence near the Andreanof Islands is approximately 73 mm (2.9 in) per year (Cross and Freymueller, 2007) and the subduction zone has ruptured in three major earthquakes in the last 60 years (fig. 1). The 1957 (M_8.6) earthquake ruptured from near the Andreanof Islands east to the Unalaska region (Johnson and others, 1994). The 1986 Andreanof Islands earthquake (M_w8.0) and the 1996 event (M_w7.9) ruptured within the western third of the 1957 rupture area. The 1996 rupture area included the region west of the Andreanof Islands and overlapped the western part of the 1986 rupture area (Tanioka and Gonzalez, 1998; fig. 1). Cross and Freymueller (2007) used GPS measurements to study plate coupling in the Andreanof region of the subduction zone and found strong along-strike variations in plate coupling. They showed that the combined rupture area of the 1986 and 1996 earthquakes was a region of high slip deficit. This combined rupture area represents the western third of the 1957 rupture zone, which had high slip during the earthquake (Johnson and others, 1994). Cross and Freymueller (2007) found that the plate interface is nearly 100 percent locked west of the 1986 and 1996 earthquakes at depths from 15–45 km (9–28 mi), and that east of the earthquakes the subduction zone is largely creeping.

According to the National Geophysical Data Center Global Historical Tsunami Database (http://doi.org/10.7289/V5PN93H7), about 50 tsunamis have affected Adak in recorded history, with maximum wave heights ranging from 1 cm (0.4 in) to 2.7 m (8.9 ft). The same database lists ten tsunamis that reached Atka, with maximum wave heights ranging from 6 cm (2.4 in) to 9.14 m (30 ft). Table 1 summarizes tsunami events that produced wave heights greater than 15 cm (0.5 ft) at Adak and Atka.

METHODOLOGY AND DATA Methodology

The regional tsunami hazard maps for Adak and Atka described in this report represent the results of the ongoing combined effort of State and Federal agencies to assist coastal communities in Alaska with tsunami hazard assessment. During recent years, tsunami inundation maps and reports have been published for a number of communities (Nicolsky and others, 2011a, 2013, 2014; Suleimani and others, 2010, 2013, 2015). In these studies, the authors performed numerical modeling of tsunami waves for each community using high-resolution digital elevation models (DEMs) of combined bathymetry and topography which have been verified with local real-time kinetic (RTK) global position system (GPS) surveys. The potential inundation resulting from various hypothetical tsunamis was simulated with the best available high-resolution data, with a typical spatial resolution of 15 m (49 ft). The authors of those reports also performed sensitivity studies to determine a possible slip distribution for the worst-case credible tsunami events. In addition, multiple constraints such as regional seismicity, tectonic processes, and geodetic and paleotsunami data were taken into account.

In this report we use a different approach because the currently available DEMs of Adak and Atka can have large horizontal and vertical discrepancies, and hence any tsunami inundation modeling might have large errors and thus may misinform emergency managers about the true location of the potential inundation zone. Nevertheless,

Table 1. Tsunami effects at Adak and Atka. Data from the National Centers for Environmental Information Global Historical Tsunami Database (http://doi.org/10.7289/V5PN93H7) and comments from Lander (1996).

Date	Magnitude (M _W)	Origin	Maximum Water Height (m)	Comments					
Adak									
04/01/1946	8.6	Unimak Island, Alaska	0.23						
11/04/1952	9.0	Kamchatka Peninsula	1.1	The waves slightly overflowed the banks of the harbor.					
03/09/1957	8.6	Aleutian Islands	2.7	Tsunami caused severe damage. All structures at the fuel and oil dock washed away up to 4 m elevation; oil pipelines damaged.					
5/22/1960	9.5	Chile	1.1						
03/28/1964	9.2	Gulf of Alaska	0.27						
02/04/1965	8.7	Rat Island	0.46	Sea level fell 1.2 feet in 15 minutes.					
11/22/1969	7.7	Kamchatka Peninsula	0.3						
05/07/1986	8.0	Andreanof Islands	0.88						
06/10/1996	7.9	Andreanof Islands	0.51						
11/15/2006	8.3	Kuril Islands	0.2						
02/27/2010	8.8	Chile	0.38						
03/11/2011	9.0	Honshu, Japan	1.1						
Atka	Atka								
03/09/1957	8.6	Alaska	9.14	Tsunami washed the skiffs up the creek and washed away all of the boathouses and also the oil supply of the village. Big pilings were washed to a height of about 10 m.					
02/27/2010	8.8	Chile	0.42						

development of an approximate tsunami inundation zone is an important task that could help to mitigate tsunami hazard in both communities. For Adak and Atka, we therefore follow the National Tsunami Hazard Mitigation Program (NTHMP) guidelines⁴ for determining tsunami hazard zones in areas that have either low risk due to small population size and minimal infrastructure vulnerability, or are not scheduled to receive high-resolution tsunami inundation maps in the near future and wish to initiate planning and preparation efforts. For the communities of Adak and Atka, we simulate a limited number of significant potential tsunamis and develop tsunami hazard maps, which are needed to support informed decision making in the event of a tsunami, and can also help with

advance development of tsunami evacuation strategies. Producing a tsunami hazard map consists of several steps, which are listed below and described in detail later in the report.

- 1. Develop computational grids. To propagate a tsunami wave from its source area to coastal locations, we use numerical grids (listed in table 2) of increasing resolution that are based on tsunami DEMs developed by the National Centers for Environmental Information (NCEI) of the National Oceanic and Atmospheric Administration (NOAA).
- 2. Identify potential tsunami sources. We identify and characterize potential tsunami sources using information on region-specific

⁴http://nws.weather.gov/nthmp/documents/Inundationareaguidelinesforlowhazardareas.pdf

Table 2. Nested grids used to compute propagation of tsunami waves generated in the Pacific Ocean to the communities of Adak and Atka. The fine-resolution grids are used to compute the inundation. Note that the grid resolution in meters is not uniform and is used to illustrate grid fineness in the Andreanof Islands region. The first dimension is the longitudinal grid resolution; the second is the latitudinal resolution.

	Resolution				
Grid Name	Arc- seconds	Meters (near Adak)	West-East Boundaries	South-North Boundaries	
Level 0, Northern Pacific	120 x 120	≈ 1,850 x 3,700	120°00' E - 100°00' W	10°00' N - 65°66' N	
Level 1, Western Aleutians	24 x 24	≈ 430 x 740	171°57'28" E - 172°10'40" W	48°43'12" N - 55°30'58" N	
Level 2, Coarse-resolution Andreanof Islands	8 x 8	≈ 150 x 250	179°34'57" E - 172°39'40" W	51°08'17" N - 52°48'58" N	
Level 3, Fine-resolution, Adak	8/3 x 8/3	≈ 48 x 82	178°18'29" W - 175°34'21" W	51°32'34" N - 52°12'27" N	
Level 3, Fine-resolution, Atka	8/3 x 8/3	≈ 48 x 83	175°24'28" W - 172°49'33" W	51°46'29" N - 52°30'10" N	

- subduction processes, geophysical data, and research models. We also use ranges of maximum considered tsunami events from previously published tsunami inundation reports (Nicolsky and others, 2011a, 2013, 2014; and Suleimani and others, 2010, 2013, 2015).
- 3. Numerically model tsunami wave propagation. We perform numerical calculations for all considered potential tsunami sources. For each scenario, we model the water dynamics in each computational grid and process numerical results from the Level 3 grids that include coastal communities of interest.
- 4. Calculate maximum composite wave heights. For each tsunami scenario, we first calculate the maximum tsunami wave heights in the highest-resolution grid over the course of the entire model run in the following way: at each grid point, tsunami wave height is computed at every time step during the tsunami propagation time, and the maximum value is retained. Then we compute the composite maximum wave height from all considered scenarios by again choosing the maximum value for each grid point among all scenarios, and plot the

- results in the vicinity of the coastal community and surrounding waters.
- 5. Extrapolate the near-shore maximum composite wave height on land. Following the above-referenced NTHMP guidelines, we extrapolate the modeling data on land to estimate the inundation zone. Specifically, we first calculate the maximum value of the tsunami height at the community and multiply this value by a safety factor. Please note that according to Synolakis and others (2007), the benchmarking of a tsunami model with the field data requires that numerical predictions for the maximum runup should not differ by more than 20 percent from the measurements. Therefore, in order to incorporate an uncertainty due to a numerical model, the safety factor needs to be at least 1.2. Similarly, in the Federal Emergency Management Agency guidelines (Applied Technology Council, 2012; Technical Report FEMA P-646), it is recommended that "the design runup elevation be taken as 1.3 times the predicted maximum runup elevation to envelop the potential variability in the estimates of modeling." In this report, we employ the same safety factor, 1.3, as in the FEMA guidelines, and then select an elevation contour corresponding to the scaled

tsunami height on a community map. The contour defines a boundary of the tsunami hazard zone and is to be used by emergency planners as a guideline for various tsunami mitigation activities.

Computational Grids and Data Sources

To develop a regional tsunami hazard map we use a series of nested computational grids. A nested grid allows for higher resolution in areas where it is needed without expending computer resources in areas where it is not. The bathymetric and topographic relief in each nested grid is based on digital elevation models (DEMs) developed at the National Centers for Environmental Information (NCEI) of the National Oceanic & Atmo-

spheric Administration (NOAA) in Boulder, Colorado. The extent of each grid used for the Adak and Atka mapping project is shown in figure 2 and listed in table 2. The coarsest grid, with 2-arc-minute (approximately 2 km) resolution, spans the central and northern Pacific Ocean. The bathymetric data for the 2-arc-minute-resolution grid is extracted from the ETOPO2 dataset (NCEI). We use two intermediate grids between the coarsest- and highest-resolution grids (table 2). The first intermediate grid of 24 arc-second resolution (Level 1) covers western Aleutian Islands. It was developed to accommodate the current tsunami mapping project for the Andreanof Islands as well as future mapping efforts for communities located on the Near Islands. The data sources and methodology used to develop 24-, 8-, and 8/3-arc-second

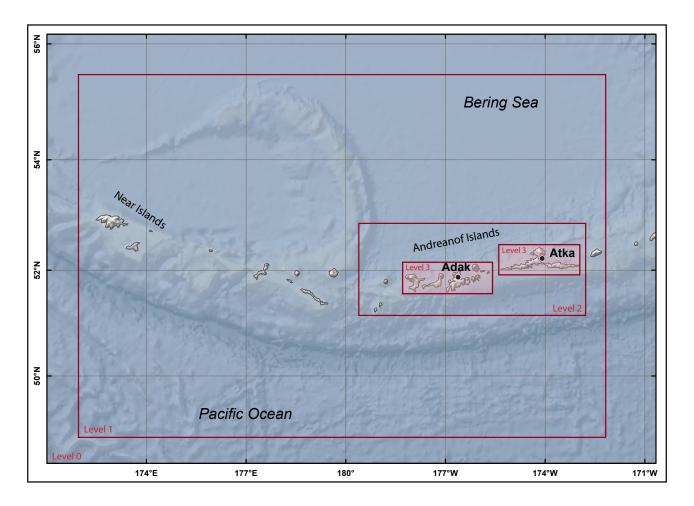


Figure 2. Nesting of the bathymetry/topography grids for numerical modeling of tsunami propagation and runup. The coarsest grid, Level 0, covers the central and northern Pacific Ocean. The location of each embedded grid is marked by a red rectangle. Refer to table 2 for grid parameters.

DEMs are described in detail by Lim and others (2011), Carignan and others (2009), and Friday and others (2011).

The fine-resolution grid for Adak covers the western Andreanof Islands including Adak Island. The fine-resolution grid for Atka covers the eastern Andreanof Islands including Atka Island. The spatial resolution of the fine-resolution grid cells, with about 48×82 m (157 × 269 ft) dimensions, satisfies NOAA minimum recommended requirements for estimation of the tsunami hazard zone (National Tsunami Hazard Mapping Program [NTHMP], 2010); however, no DEM verification efforts were conducted to reduce uncertainties in the fine-resolution (level 3) Atka and Adak grids. Therefore, in this report we do not perform high-resolution runup modeling, but provide an estimation of the tsunami hazard zone by extrapolating the maximum composite tsunami wave height on land according to the tsunami scenarios described below. We account for uncertainties inherent to this method by applying the safety factor to the estimated hazard zone.

Tsunami Sources

In this project we employ a deterministic method to develop potential tsunami sources, which is distinctly different from the probabilistic tsunami hazard analysis used in projects with different objectives, such as land-use planning or insurance estimates (Geist and Parsons, 2006). Alaska tsunami hazard maps are produced on the basis of significant credible tsunami scenarios for a given segment of the coastline. Although we do not develop worst-case credible tsunami scenarios in this report as we have in some previous reports, we use the same underlying assumptions and results regarding the maximum considered scenarios for other locations along the Alaska–Aleutian subduction zone.

In this regional tsunami hazard assessment project we consider three characteristic tsunami scenarios that produced simulated devastating waves at other Alaska coastal communities (Nicolsky and others, 2015; Suleimani and others,

2016). These potential ruptures, with a uniform slip distribution along the strike, are positioned on the Alaska–Aleutian subduction interface south of the communities of Adak and Atka. The three sources differ in the downdip slip distribution pattern such that the depth range at which the maximum slip occurs varies from the shallow region, close to the trench, to the deeper parts of the plate interface. All ruptures have the same extent, which is determined by the location of communities and constrained by the seismic moment. We construct the scenarios using the following procedure:

- 1. We place hypothetical ruptures on the megathrust and determine their lengths. In this report, the hypothetical ruptures extend from about 179°30' W to 171° W in the along-strike direction. Both Adak and Atka are located within this rupture length.
- 2. To simulate potential tsunami sources on the Alaska–Aleutian megathrust, we employ a discretized model (Nicolsky and others, 2015) of the Alaska–Aleutian plate interface (Hayes and others, 2012) between the subducting and overriding plates. To define coseismic slip of hypothetical ruptures in the downdip direction, we use either a previously considered slip distribution or parameterize it by formulas according to Freund and Barnett (1976).
- 3. We allow a maximum slip of 46 m (151 ft) in the shallow part of the rupture, and a maximum slip of 35 m (115 ft) in deeper areas. The assumed maximum slip of 35–37 m (115–121 ft) in deeper parts of the rupture is consistent with other modeling studies (such as Butler, 2014) for this region.

Below we describe the significant credible tsunami sources for Adak and Atka. The proposed slip distributions for these scenarios are shown in figure 3; vertical coseismic deformations are shown in figure 4. The main rupture parameters and amount of permanent subsidence in the communities are listed in Table 3.

	Scenarios	Depth range, km (mi)	Maximum slip depth range, km (mi)	Maximum slip, m (ft)	Maximum regional subsidence, m (ft)	Maximum regional uplift, m (ft)	Actual subsidence in Adak, m (ft)	Actual subsidence in Atka, m (ft)
1	Mw 9.0 earthquake: SAFRR-type event, slip near the trench	8-54 (5-33)	11-14 (7- 8.5)	55-65 (180- 213)	-2.7 (-8.8)	13.8 (45.3)	-0.9 (-2.9)	-0.6 (-1.9)
2	Mw 9.0 earthquake: Maximum slip at 15-25 km (9.3-15.5 mi) depth	5-35 (3- 21.7)	15-25 (9.3- 15.5)	34-35 (111- 115)	-6.4 (-21.0)	13.6 (44.6)	-1.4 (-4.6)	-1.0 (-3.3)
3	Mw 9.0 earthquake: Maximum slip at 25-35 km (15.5-21.7 mi) depth	14-45 (8-26)	25-35 (15.5- 21.7)	34-35 (111- 115)	-5.6 (-18.3)	17.6 (57.7)	-2.9 (-9.5)	-2.3 (-7.5)

Table 3. Significant credible tsunami sources for Adak and Atka.

Scenario 1. M_w9.0 earthquake: SAFRR-type event

This event is a hypothetical Tohoku-type M_9.0 earthquake rupturing the Alaska-Aleutian megathrust. During the 2011 Tohoku earthquake a large amount of slip occurred between the subducting and overriding plates near the Japan trench (Fujii and others, 2011; Shao and others, 2011). The USGS Science Application for Risk Reduction (SAFRR) project, in collaboration with NOAA and State of California agencies, developed a plausible hypothetical tsunami scenario (Kirby and others, 2013) to describe the impacts of a tsunami generated by an earthquake in the Alaska Peninsula region (Ross and others, 2013). For Scenario 1 in this report we assume that the slip distribution in the downdip direction is the same as that in the SAFRR source, where greater slip occurs closer to the trench. This hypothetical rupture is positioned across the shelf area from the communities of Adak and Atka. The slip is distributed almost uniformly along the strike except for the edges of the rupture where it tapers. The maximum slip of 46 m (151 ft) is at a depth of 5–15 km (3.1–9.3 mi). The proposed slip distribution is shown in figure 3A; vertical coseismic deformations for this scenario are shown in figure 4A.

Scenario 2. M 9.0 earthquake: Maximum slip at 15–25 km (9.3–15.5 mi) depth This event is a hypothetical M_w 9.0 earthquake rupturing the Alaska–Aleutian megathrust. The slip is distributed almost uniformly along strike except for the edges of the rupture where it tapers. The maximum slip of 35 m (114.8 ft) is at a depth of 15–25 km (9.3–15.5 mi). The proposed slip distribution is shown in figure 3B; vertical coseismic deformations for this scenario are shown in figure 4B.

Scenario 3. M_w9.0 earthquake: Maximum slip at 25–35 km (15.5– 21.7 mi) depth This event is a hypothetical $M_w 9.0$ earthquake rupturing the Alaska–Aleutian megathrust. The slip is distributed almost uniformly along strike except for the edges of the rupture where it tapers. The maximum slip of 35 m (114.8 ft) is at a depth of 25–35 km (15.5–21.7 mi). The proposed slip distribution is shown in figure 3C; vertical coseismic deformations for this scenario are shown in figure 4C.

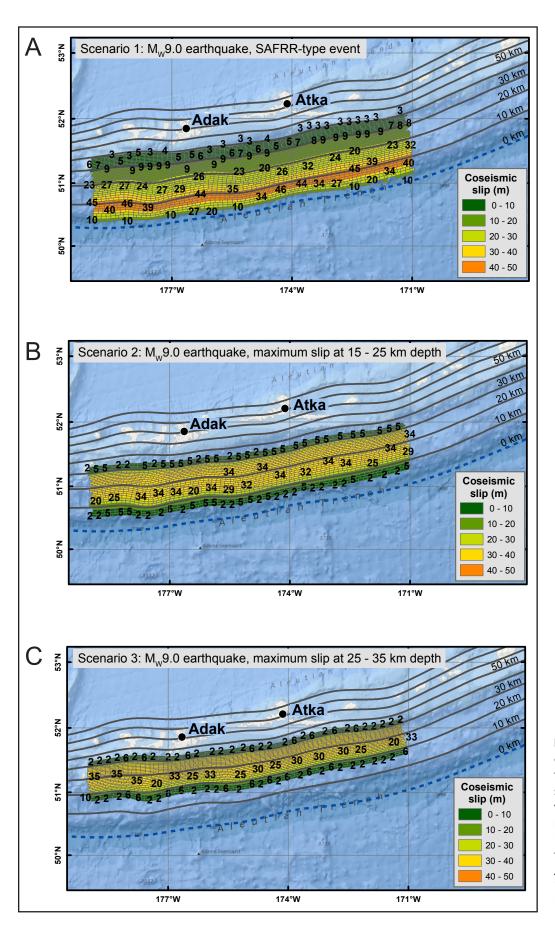


Figure 3. Proposed slip distributions along the plate interface for scenarios 1-3. Slip values in meters are marked by small black labels. The depth contours of the Alaska-Aleutian subduction interface are shown by gray lines.

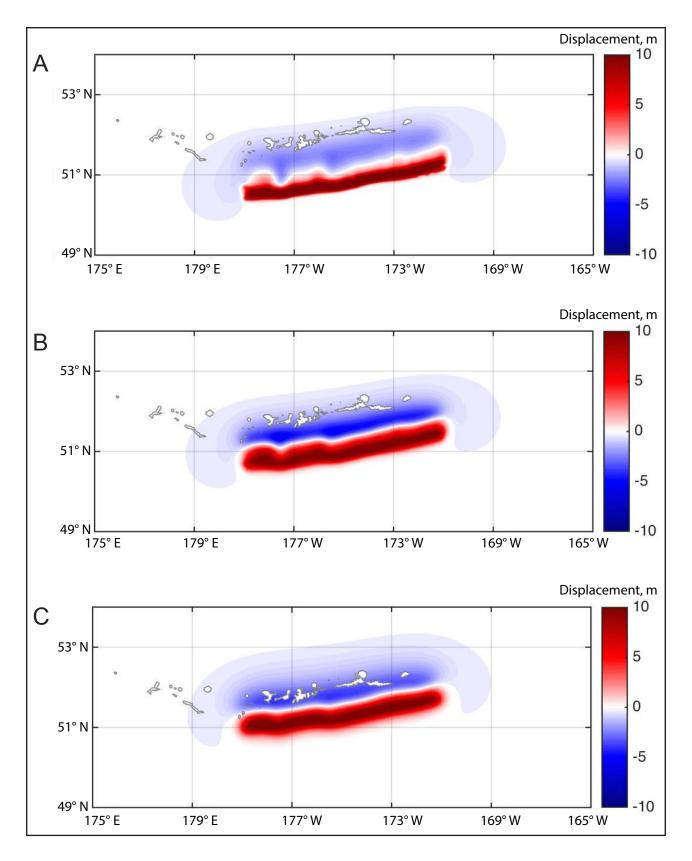


Figure 4. Vertical coseismic deformations corresponding to scenarios 1-3. Blue areas are associated with coseismic ground subsidence; areas of uplift are shown in red.

Numerical Model of Tsunami Propagation and Runup

The numerical model currently used by the Alaska Earthquake Center (AEC) for tsunami inundation mapping is a nonlinear, flux-formulated, shallow-water model (Nicolsky and others, 2011b) that has been validated (NTHMP, 2012) through a set of analytical benchmarks and tested against laboratory and field data (Synolakis and others, 2007). The application of the model to tsunami inundation mapping of Alaska coastal communities, including its assumptions and limitations, is described in a number of previous tsunami reports; see Suleimani and others (2010, 2013, 2015) and Nicolsky and others (2011a, 2013, 2014). In this study, we conduct all model runs using bathymetric data that correspond to the Mean Higher High Water (MHHW) tide level in Adak and Atka.

MODELING RESULTS

We performed numerical calculations for the three scenarios described above. For each scenario, we modeled the water dynamics for each grid listed in table 2 and computed maximum tsunami wave heights in the level 3 grids for Adak and Atka. Each model run was performed for 6 hours of tsunami propagation to account for all waves in the wave train, as well as for secondary (reflected) waves. Figures 5 and 6 show the maximum tsunami wave heights for scenarios 1-3 for the Adak and Atka grids, respectively. We emphasize here that the tsunami wave heights are calculated offshore and they differ from the runup heights, which are the land elevations reached by the waves. In both regions the highest tsunami amplitudes are present along the Pacific shore of the Andreanof Islands, while the Bering Sea coast experiences smaller waves due to the natural barrier of the island chain.

We show the maximum composite tsunami height for all scenarios, calculated for the vicinity of Adak, in figure 7. In this region (fig. 7), the absolute maximum value of the tsunami height with respect to MHHW is 18 m (59 ft); multiplied by a safety factor of 1.3 it predicts 23.4 m

(76.8 ft) for the maximum estimated runup height for the community of Adak. We present in figure 8 the maximum composite tsunami height for all scenarios, calculated for the vicinity of Atka. The absolute maximum value of the tsunami height in this region is 23.9 m (78.4 ft); multiplied by a safety factor of 1.3 it predicts 31.1 m (102 ft) for the maximum estimated runup height for the community of Atka.

Map sheets 1 and 2 illustrate approximate tsunami hazard maps for the communities of Adak and Atka, respectively, and indicate that most of the buildings and infrastructure in each community are within the potential tsunami inundation zone. For each community, we draw an elevation contour on the community topographic map that corresponds to the maximum estimated runup height. This contour approximates the boundary of the tsunami hazard zone and could be used by emergency planners and public officials as a guideline in tsunami mitigation activities. For Atka (map sheet 2), we used the DCRA elevation dataset based on the digital orthophoto of the community. The closest contour to the maximum runup height of 31.1 m (102 ft) was at the elevation of 31 m (102.55 ft) and therefore was extracted as the tsunami hazard boundary. No DCRA elevation data existed for Adak, and therefore we extracted the elevation contour of 23 m (78.4 ft) from the 3-arc-second DEM of Adak used in the tsunami modeling process. A reader can refer to the metadata that accompanies the report for more details.

To help emergency managers assess the tsunami hazard in Adak and Atka, we supplement the hazard maps with time series of the modeled water level at a nearshore location in each community. These locations are shown by black triangles in figures 7 and 8, and the time series plots are shown in figure 9. Zero time corresponds to the time when the earthquake occurs. To compare the height of arriving tsunamis for different scenarios, which result in different values of land subsidence, we use a vertical datum with a zero mark corresponding to the post-earthquake sea level. Figure 9 shows that the tsunami wave heights at Atka are compa-

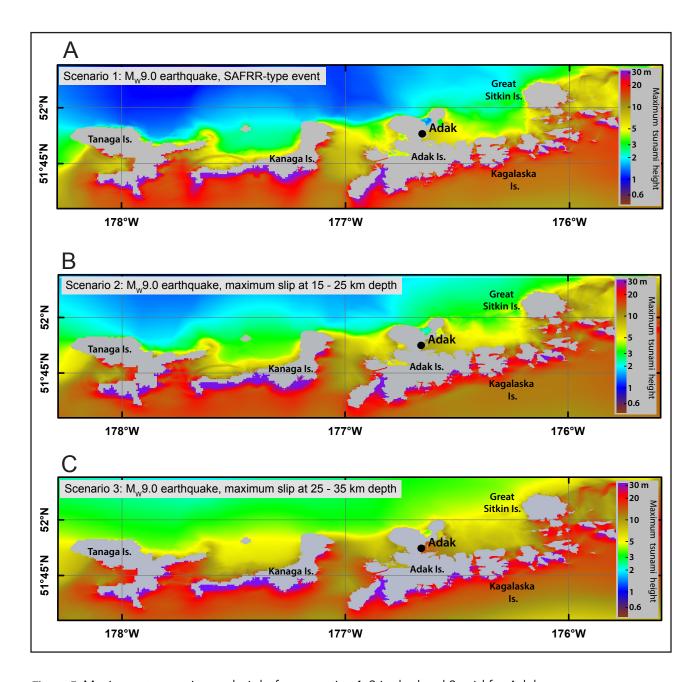


Figure 5. Maximum tsunami wave height for scenarios 1-3 in the level 3 grid for Adak.

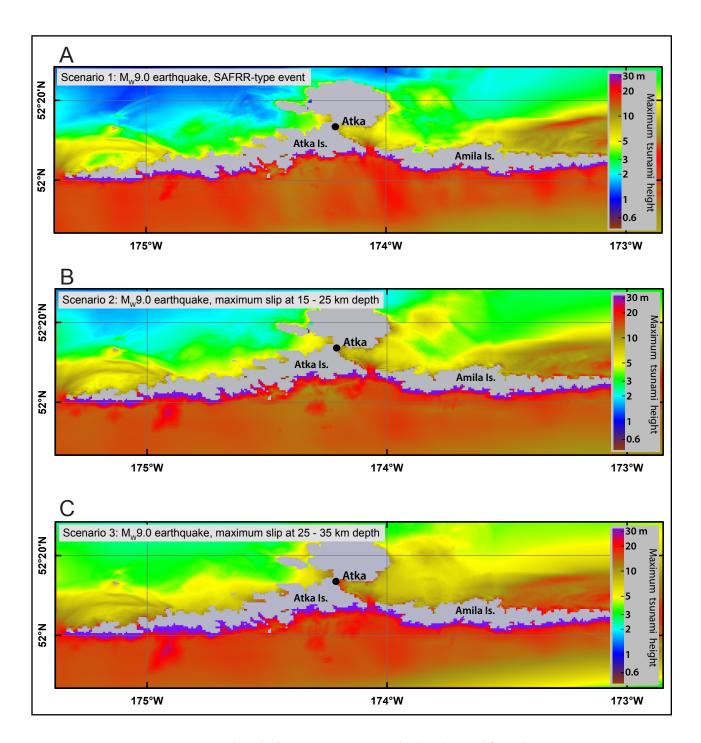


Figure 6. Maximum tsunami wave height for scenarios 1-3 in the level 3 grid for Atka.

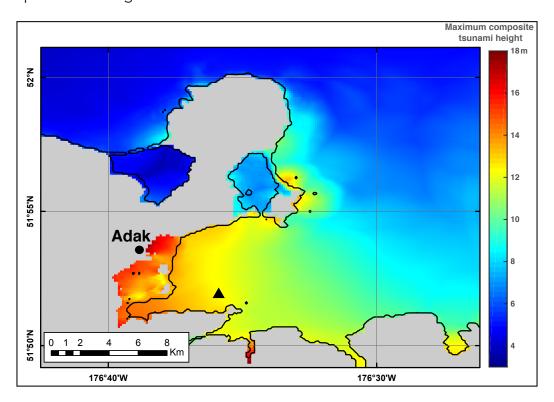


Figure 7. Maximum composite tsunami wave height at Adak. The black triangle indicates the location of the time series point, and the black line is the MHHW shoreline.

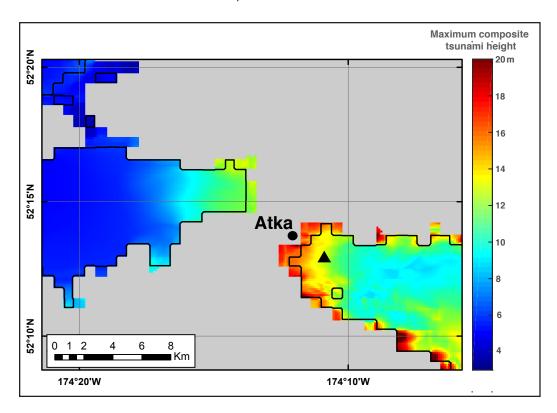


Figure 8. Maximum composite tsunami wave height at Atka. The black triangle indicates the location of the time series point, and the black line is the MHHW shoreline. The low resolution of the shoreline is an artifact of the original level 3 grid for Atka, which was developed by NCEI and had a low-resolution coastline.

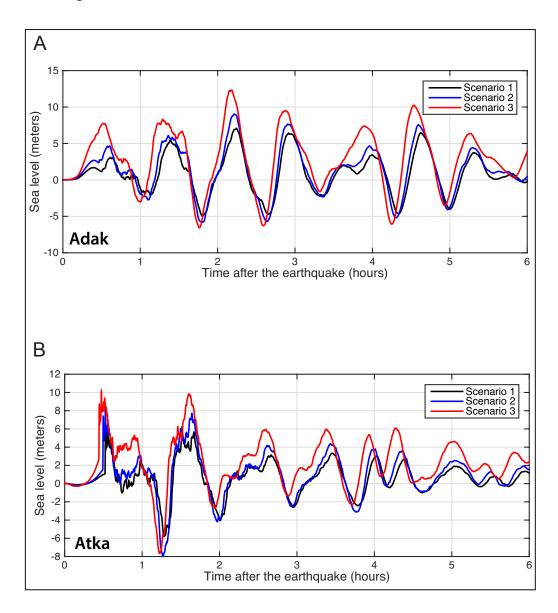


Figure 9. Time series of water level for scenarios 1–3 at Adak (A) and Atka (B) calculated at the locations shown as black triangles in figures 7 and 8.

rable to the observed water levels during the 1957 tsunami (table 1), while at Adak the simulated tsunami wave heights are much higher than anything recorded. Analysis of the time series plots shows that scenario 3 results in the highest waves at both locations. Also, the time series plots demonstrate that waves of dangerously high amplitudes might be arriving for at least 6 hours.

In addition to the time series of the simulated water level, we have also modeled the potential permanent subsidence in Adak and Atka. The yellow line in map sheets 1 and 2 shows the

post-earthquake MHHW shoreline after ground subsidence in Adak and Atka, respectively. Scenario 3 results in the maximum subsidence of 2.9 m (9.5 ft) in Adak and 2.3 m (7.5 ft) in Atka (table 3). Most low-lying areas in Adak could be permanently flooded as a result of this hypothetical earthquake, while the permanently flooded area in Atka includes only a narrow band of land along the shoreline.

SUMMARY

We present the results of modeling earthquake-generated tsunamis in the Andreanof Islands region, Alaska, and their effects on the communities of Adak and Atka. We numerically model tsunami waves generated by local hypothetical tectonic sources, analyze tsunami-wave dynamics in the vicinity of the communities, and develop tsunami hazard maps. Specifically, we compute the composite maximum wave height from all considered scenarios and follow the NTHMP guidelines to extrapolate the modeling data on land for estimation of tsunami inundation. The maximum estimated runup heights that include the recommended safety factor are 23.4 m (76.8 ft) and 31.1 m (102 ft) for the communities of Adak and Atka, respectively.

The tsunami inundation approximations shown on the tsunami hazard maps have been completed using the best information available and are believed to be accurate; however, their preparation required many assumptions. In this assessment, we estimate the potential tsunami inundation zone based on three significant tsunami scenarios. Although the modeled tsunami inundation cannot be considered exhaustive, the modeling results are still thought to provide a sound approximation to the potential tsunami inundation zone in the communities. Note that actual conditions during a tsunami event may vary from those considered, so the accuracy cannot be guaranteed. The

limits of inundation shown should be used only as a guideline for emergency planning and response action. Actual areas inundated will depend on specifics of earth deformation, land construction, and tide level, and may differ from areas shown on the map. The information on the hazard maps is intended to assist state and local agencies in planning emergency evacuation and tsunami response actions in the event of a major tsunamigenic earthquake. These results are not intended for land-use regulation or building-code development.

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